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Emergence of oscillations in a two-layer cascade

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Joint work with Elisenda Feliu

MPI MiS

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MAPK cascade





 The mitogen-activated protein kinase (MAPK) cascades are processes of cell signalling, present in all eukaryotic cells.

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MAPK cascade





- The mitogen-activated protein kinase (MAPK) cascades are processes of cell signalling, present in all eukaryotic cells.
- The Huang and Ferrell model consists on several layers where the activated kinase at each level, phosphorylates the kinase in the next one

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MAPK Cascade





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MAPK Cascade





Chemical Reaction Network

$$\begin{split} & \mathbf{S}_{0} + \mathbf{E} \underbrace{\frac{\kappa_{1}}{\kappa_{2}}}_{\mathbf{K}_{2}} \mathbf{Y}_{1} \xrightarrow{\kappa_{3}} \mathbf{S}_{1} + \mathbf{E} \\ & \mathbf{S}_{1} + \mathbf{F}_{1} \underbrace{\frac{\kappa_{4}}{\kappa_{5}}}_{\mathbf{K}_{5}} \mathbf{Y}_{2} \xrightarrow{\kappa_{6}} \mathbf{S}_{0} + \mathbf{F}_{1} \\ & \mathbf{P}_{0} + \mathbf{S}_{1} \underbrace{\frac{\kappa_{7}}{\kappa_{8}}}_{\mathbf{K}_{8}} \mathbf{Y}_{3} \xrightarrow{\kappa_{9}} \mathbf{P}_{1} + \mathbf{S}_{1} \\ & \mathbf{P}_{1} + \mathbf{F}_{2} \underbrace{\frac{\kappa_{10}}{\kappa_{11}}}_{\mathbf{K}_{11}} \mathbf{Y}_{4} \xrightarrow{\kappa_{12}} \mathbf{P}_{0} + \mathbf{F}_{2}. \end{split}$$

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MAPK Cascade





Chemical Reaction Network

- $S_{0} + E \xrightarrow{\kappa_{1}}{\kappa_{2}} Y_{1} \xrightarrow{\kappa_{3}} S_{1} + E$ $S_{1} + F_{1} \xrightarrow{\kappa_{4}}{\kappa_{5}} Y_{2} \xrightarrow{\kappa_{6}} S_{0} + F_{1}$ $P_{0} + S_{1} \xrightarrow{\kappa_{7}}{\kappa_{8}} Y_{3} \xrightarrow{\kappa_{9}} P_{1} + S_{1}$ $P_{1} + F_{2} \xrightarrow{\kappa_{10}}{\kappa_{11}} Y_{4} \xrightarrow{\kappa_{12}} P_{0} + F_{2}.$
- Finite directed graph with no loops.
- Nodes: nonnegative integer linear combinations of the species.



The evolution of the concentration of the species can be modelled with a system of ODEs that, under mass action kinetics, are polynomial. The coefficients of the polynomial equations are $\{\kappa_1, \ldots, \kappa_m\} \subset \mathbb{R}^n_{>0}$ which are called *rate constants*.



The evolution of the concentration of the species can be modelled with a system of ODEs that, under mass action kinetics, are polynomial. The coefficients of the polynomial equations are $\{\kappa_1, \ldots, \kappa_m\} \subset \mathbb{R}^n_{>0}$ which are called *rate constants*.

Key characteristics of the system of ODEs

- One autonomous differential equation per species.
- ► As many monomials as linear combinations appearing in the nodes.
- As many parameters as rate constants.

ODEs for Reaction Networks



For our system

$$\begin{split} \mathbf{S}_{0} + \mathbf{E} &\stackrel{\kappa_{1}}{\overleftarrow{\kappa_{2}}} \mathbf{Y}_{1} \xrightarrow{\kappa_{3}} \mathbf{S}_{1} + \mathbf{E} \\ \mathbf{S}_{1} + \mathbf{F}_{1} &\stackrel{\kappa_{4}}{\overleftarrow{\kappa_{5}}} \mathbf{Y}_{2} \xrightarrow{\kappa_{6}} \mathbf{S}_{0} + \mathbf{F}_{1} \\ \mathbf{P}_{0} + \mathbf{S}_{1} &\stackrel{\kappa_{7}}{\overleftarrow{\kappa_{8}}} \mathbf{Y}_{3} \xrightarrow{\kappa_{9}} \mathbf{P}_{1} + \mathbf{S}_{1} \\ \mathbf{P}_{1} + \mathbf{F}_{2} &\stackrel{\kappa_{10}}{\overleftarrow{\kappa_{11}}} \mathbf{Y}_{4} \xrightarrow{\kappa_{12}} \mathbf{P}_{0} + \mathbf{F}_{2}. \end{split}$$

$$\begin{split} s_0 &= -\kappa_1 s_0 \varepsilon + \kappa_2 y_1 + \kappa_6 y_2 \\ s_1 &= -\kappa_4 s_1 f_1 - \kappa_7 s_1 p_0 + \kappa_3 y_1 + \kappa_5 y_2 + \kappa_8 y_3 + \kappa_9 y_3 \\ \dot{p}_0 &= -\kappa_7 s_1 p_0 + \kappa_8 y_3 + \kappa_1 y_4 \\ \dot{p}_1 &= -\kappa_1 s_0 \varepsilon + \kappa_2 y_1 + \kappa_3 y_1 \\ \dot{f}_1 &= -\kappa_4 s_1 f_1 + \kappa_5 y_2 + \kappa_6 y_2 \\ \dot{f}_2 &= -\kappa_1 s_0 \rho_1 f_2 + \kappa_1 y_1 + \kappa_1 y_2 4 \\ \dot{y}_1 &= \kappa_1 s_0 \varepsilon - \kappa_2 y_1 - \kappa_3 y_1 \\ \dot{y}_2 &= \kappa_4 s_1 f_1 - \kappa_5 y_2 - \kappa_6 y_2 \\ \dot{y}_3 &= \kappa_7 s_1 \rho_0 - \kappa_8 y_3 - \kappa_9 y_3 \\ \dot{y}_4 &= \kappa_1 s_0 \rho_1 f_2 - \kappa_1 y_4 - \kappa_1 y_4 \end{split}$$

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$$\dot{s}_0 = -\kappa_1 s_0 e + \kappa_2 y_1 + \kappa_6 y_2$$

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Consider a system of ODEs parametrized by $\mu \in \mathbb{R}$:

$$\dot{x}=f_{\mu}(x),$$

where $x \in \mathbb{R}^n$, and $f_{\mu}(x)$ varies smoothly in μ and x. Assume that $f_{\mu_0}(x_0) = 0$, and assume that there is a smooth curve of steady states:

$$\mu \mapsto x(\mu)$$

(that is, $f_{\mu}(x(\mu)) = 0$ for all μ) such that $x(\mu_0) = x_0$.



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(that is, $f_{\mu}(x(\mu)) = 0$ for all μ) such that $x(\mu_0) = x_0$.

A simple Hopf bifurcation occurs at μ_0 if the matrix $J_f(x_0, \mu_0)$ has a simple pair of imaginary eigenvalues, while all other eigenvalues remain with negative real part.



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Example

Consider the system of ODEs

$$\dot{x} = -y + x(\mu - x^2 - y^2)$$

 $\dot{y} = x + y(\mu - x^2 - y^2)$

The only steady state is (0,0) which is independent of μ .



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The only steady state is (0,0) which is independent of μ . We have

$$J_f((0,0),\mu) = \left[egin{array}{cc} \mu & -1 \ 1 & \mu \end{array}
ight]$$

with eigenvalues $-i + \mu$ and $i + \mu$.



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Example

Consider the system of ODEs

$$\dot{x} = -y + x(\mu - x^2 - y^2)$$

 $\dot{y} = x + y(\mu - x^2 - y^2)$

The dynamics of the system change depending on the value of μ .





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Our goal...

Decide whether there are values for the parameters such that a Hopf bifurcation arises in the subsystem.



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Ingredients







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Decide whether there are values for the parameters such that a Hopf bifurcation arises in the subsystem.

Ingredients

- Equilibria
- Are the dynamics constrained to a lower-dimensional space?



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Our goal...

Decide whether there are values for the parameters such that a Hopf bifurcation arises in the subsystem.

Ingredients

- Equilibria
- Are the dynamics constrained to a lower-dimensional space?
- Eigenvalues of the Jacobian of the polynomials defining the ODEs at equilibrium

Equilibria for CRN



The positive steady states are defined as equilibrium points of the ODE that have positive entries. That is, the points in $\mathbb{R}^n_{>0}$ such that $\dot{x} = 0$.

Equilibria for CRN



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Example

For our system, the positive steady states are defined by the equations

$$0 = -\kappa_1 s_0 e + \kappa_2 y_1 + \kappa_6 y_2$$

$$0 = -\kappa_4 s_1 f_1 - \kappa_7 s_1 p_0 + \kappa_3 y_1 + \kappa_5 y_2 + \kappa_8 y_3 + \kappa_9 y_3$$

$$0 = -\kappa_7 s_1 p_0 + \kappa_8 y_3 + \kappa_{12} y_4$$

$$0 = -\kappa_1 s_0 e + \kappa_2 y_1 + \kappa_3 y_1$$

$$0 = -\kappa_4 s_1 f_1 + \kappa_5 y_2 + \kappa_6 y_2$$

$$0 = -\kappa_1 s_0 e - \kappa_2 y_1 - \kappa_3 y_1$$

$$0 = \kappa_4 s_1 f_1 - \kappa_5 y_2 - \kappa_6 y_2$$

$$0 = \kappa_7 s_1 p_0 - \kappa_8 y_3 - \kappa_9 y_3$$

$$0 = \kappa_1 s_0 p_1 f_2 - \kappa_1 y_4 - \kappa_{12} y_4$$

$$s_0, s_1, p_0, p_1, e, f_1, f_2, y_i \in \mathbb{R}_+^n$$



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The steady states can be parameterized as

$$\begin{aligned} \varphi(s_0, s_1, p_1, f_1, y_3) &= \left(s_0, s_1, \frac{(k_8 + k_9)y_3}{k_7 s_1}, p_1, \frac{(k_2 + k_3)k_4 k_6 s_1 f_1}{k_1 k_3 (k_5 + k_6) s_0}, f_1, \frac{k_9 (k_{11} + k_{12}) y_3}{k_{10} k_{12} p_1}, \\ &\frac{\kappa_4 \kappa_6 s_1 f_1}{\kappa_3 (\kappa_5 + \kappa_6)}, \frac{\kappa_4 s_1 f_1}{\kappa_5 + \kappa_6}, y_3, \frac{\kappa_9 y_3}{\kappa_{12}}\right) \end{aligned}$$

Conservation laws in CRN



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Given an initial solution x_0 for the system of ODEs, the trajectories containing x_0 , remain in $x_0 + S$ for a linear space *S* (*Stoichiometric compatibility class*). Therefore, we study the dynamics of the network within $x_0 + S$.

Conservation laws in CRN



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Given an initial solution x_0 for the system of ODEs, the trajectories containing x_0 , remain in $x_0 + S$ for a linear space *S* (*Stoichiometric compatibility class*). Therefore, we study the dynamics of the network within $x_0 + S$.

Example

In our system the compatibility classes are defined by the equations

$$s_{0} + s_{1} + y_{1} + y_{2} + y_{3} = T_{1}$$

$$p_{0} + p_{1} + y_{3} + y_{4} = T_{2}$$

$$e + y_{1} = T_{3}$$

$$f_{1} + y_{2} = T_{4}$$

$$f_{2} + y_{4} = T_{5}.$$

These come precisely from the linear relations among the equations defining the system of ODEs.

Conservation laws in CRN



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Indeed, consider the conservation law

$$f_2+y_4=T_5.$$

The ODEs associated with f_2 and y_4 are

$$\dot{f}_2 = -\kappa_{10} p_1 f_2 + \kappa_{11} y_4 + \kappa_{12} y_4 \dot{y}_4 = \kappa_{10} p_1 f_2 - \kappa_{11} y_4 - \kappa_{12} y_4$$

whose sum vanishes, that is, $\dot{f}_2 + \dot{y_4} = 0$, which implies the conservation law above.

Dynamics of CRN



Intuitively...





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There is hope!

There is no need to compute the exact value of the eigenvalues

Liu's criterion for Hopf bifurcations



Denote the characteristic polynomial of $J_{f_{\mu}}(x(\mu))$ as

$$p_{\mu}(\lambda) := \det \left(\lambda I - J_{f_{\mu}}\right)|_{x=x(\mu)} = \lambda^n + b_1(\mu)\lambda^{n-1} + \cdots + b_n(\mu).$$

Since the coefficients of $p_{\mu}(\lambda)$ depend on μ , its Hurwitz determinants depend on μ as well. We denote each determinant by $H_i(\mu)$, for i = 1, ..., n.



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Since the coefficients of $p_{\mu}(\lambda)$ depend on μ , its Hurwitz determinants depend on μ as well. We denote each determinant by $H_i(\mu)$, for i = 1, ..., n.

Liu's criterion

There is a simple Hopf bifurcation at x_0 with respect to μ if and only if the following conditions hold:

1. $b_n(\mu_0) > 0$, 2. $H_1(\mu_0) > 0$, $H_2(\mu_0) > 0$, ..., $H_{n-2}(\mu_0) > 0$, and 3. $H_{n-1}(\mu_0) = 0$ and $\frac{d(H_{n-1}(\mu))}{d\mu}|_{\mu=\mu_0} \neq 0$.



Definition (Hurwitz determinants)

Let $p(x) = a_s x^s + a_{s-1} x^{s-1} + \ldots + a_1 x + a_0$ be a polynomial with $a_i \in \mathbb{R}$, $a_s > 0$ and $a_0 \neq 0$. Define the Hurwitz matrix associated with p, as the matrix H whose entries are defined by $h_{i,j} = a_{s-2i+j}$ for $i, j = 1, \ldots, s$ and $a_k = 0$ if k < 0 or k > s:

$$H = \begin{pmatrix} a_{s-1} & a_s & 0 & 0 & \cdots & 0 \\ a_{s-3} & a_{s-2} & a_{s-1} & a_s & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & a_{6-s} & \cdots & a_2 \\ 0 & 0 & 0 & 0 & \cdots & a_0 \end{pmatrix}$$

The *i*-th Hurwitz determinant of H, denoted by H_i , is defined as $H_i = \det(H_{I,I})$, with $I = \{1, \ldots, i\}$.



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Results

The characteristic polynomial of the Jacobian restricted to a stoichiometric compatibility class has degree 6.



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Results

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- ▶ We computed 6 Hurwitz determinants: {*H*₁,..., *H*₆} and evaluated them at the parameterization of the steady states.
- ► H₁, H₂, H₃, and H₆ are rational functions (in 6 variables and 17 parameters) with positive coefficients.
- ► H₄ and H₅ are rational functions whose coefficients can have positive and negaive values.

A Hopf bifurcation appears if there is a set of parameters κ^* and an steady state x^* such that

$$H_4(k^*, x^*) \ge 0$$
 and $H_5(k^*, x^*) = 0$.



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Proposition

For a real, multivariate polynomial

$$p(x) = a_1 x^{\alpha_1} + a_2 x^{\alpha_2} + \cdots + a_\ell x^{\alpha_\ell} \in \mathbb{R}[x_1, \ldots, x_n],$$

if α_i is a vertex of Newt(p), then there exists $x^* \in \mathbb{R}^n_{>0}$ such that $sign(p(x^*)) = sign(a_i)$.



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$$p(x) = a_1 x^{\alpha_1} + a_2 x^{\alpha_2} + \cdots + a_\ell x^{\alpha_\ell} \in \mathbb{R}[x_1, \ldots, x_n],$$

if α_i is a vertex of Newt(p), then there exists $x^* \in \mathbb{R}^n_{>0}$ such that $sign(p(x^*)) = sign(a_i)$.

Proposition

Let $f, g \in \mathbb{R}[x_1, x_2, \dots, x_s]$. Assume that α is a positive vertex of Newt(f), β_+ is a positive vertex of Newt(g), and β_- is a negative vertex of Newt(g). Then, if $\operatorname{int}(N_f(\alpha)) \cap \operatorname{int}(N_g(\beta_+))$ and $\operatorname{int}(N_f(\alpha)) \cap \operatorname{int}(N_g(\beta_-))$ are both nonempty, then there exists $x^* \in \mathbb{R}^s_{>0}$ such that $f(x^*) > 0$ and $g(x^*) = 0$.

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Applying the previous propositions in a reduced version of H_4 and H_5 we found the following parameters that satisfy Liu's criterion.

 $s_0 = 0.008221823730, s_1 = 8.670580350 \times 10^{-7}, p_0 = 1, p_1 = 197868.6638,$ $e = 0.007561436673, f_1 = 1, f_2 = 0.007884719363, y_1 = 0.001238422300,$ $y_2 = 0.001238422300, y_3 = 0.5461508658, y_4 = 780.0694426$

with parameters

$$\begin{split} \kappa_1 = & 20, \kappa_2 = 0.004, \kappa_3 = 1, \kappa_4 = 1428.303957, \kappa_5 = 9.941572972 \times 10^{-8} \\ \kappa_6 = & 1, \kappa_7 = 9.941572972 \times 10^8, \kappa_8 = 150, \kappa_9 = 1428.303957, \\ \kappa_{10} = & 1, \kappa_{11} = 1, \kappa_{12} = 1, \\ T_1 = & 0.5568504012, T_2 = 198650.2794, \\ T_3 = & 0.008799858973, T_4 = 1.001238422, T_5 = 780.0773273 \end{split}$$





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Remaining questions



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References

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Ultrasensitivity in the mitogen-activated protein kinase cascade. *Proc. Natl. Acad. Sci. U.S.A.*, 93:10078–10083, 1996

L. Qiao, R. B. Nachbar, I. G. Kevrekidis, and S. Y. Shvartsman. Bistability and oscillations in the Huang-Ferrell model of MAPK signaling.

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