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# **Emergence of oscillations in a two-layer cascade**

#### Angélica Torres

*Joint work with Elisenda Feliu*

MPI MiS

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### **MAPK cascade**



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 $\blacktriangleright$  The mitogen-activated protein kinase (MAPK) cascades are processes of cell signalling, present in all eukaryotic cells.

 $\mathbf{A} \equiv \mathbf{B} + \mathbf{A} \mathbf{B} + \mathbf{A} \mathbf{B} + \mathbf{A} \mathbf{B} + \mathbf{B}$ 

### **MAPK cascade**





- $\blacktriangleright$  The mitogen-activated protein kinase (MAPK) cascades are processes of cell signalling, present in all eukaryotic cells.
- The Huang and Ferrell model consists on several layers where the activated kinase at each level, phosphorylates the kinase in the next one

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#### **MAPK Cascade**



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#### **MAPK Cascade**





#### **Chemical Reaction Network**

 $S_0 + E \xrightarrow[\kappa_2]{\kappa_1} Y_1 \xrightarrow{\kappa_3} S_1 + E$  $S_1 + F_1 \xrightarrow[\kappa_5]{\kappa_4} Y_2 \xrightarrow{\kappa_6} S_0 + F_1$  $P_0 + S_1 \xrightarrow[\kappa_8]{\kappa_7} Y_3 \xrightarrow{\kappa_9} P_1 + S_1$  $P_1 + F_2 \xrightarrow[\kappa_{10}]{\kappa_{10}} Y_4 \xrightarrow[\kappa_{12}]{\kappa_{12}} P_0 + F_2.$ 

 $A \equiv 1 + 4 \sqrt{10} \times 1 + 2 \times 1 + 2 \times 1 + 2$ 

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#### **MAPK Cascade**





#### **Chemical Reaction Network**

- $S_0 + E \xrightarrow[\kappa_2]{\kappa_1} Y_1 \xrightarrow{\kappa_3} S_1 + E$  $S_1 + F_1 \xrightarrow[\kappa_5]{\kappa_4} Y_2 \xrightarrow{\kappa_6} S_0 + F_1$  $P_0 + S_1 \xrightarrow[\kappa_8]{\kappa_7} Y_3 \xrightarrow{\kappa_9} P_1 + S_1$  $P_1 + F_2 \xrightarrow[\kappa_{10}]{\kappa_{10}} Y_4 \xrightarrow[\kappa_{12}]{\kappa_{12}} P_0 + F_2.$
- Finite directed graph with no loops.
- ▶ Nodes: nonnegative integer linear combinations of the species.

**KORKARA REPASA DA VOCA** 



**KORKARA REPASA DA VOCA** 

The evolution of the concentration of the species can be modelled with a system of ODEs that, under mass action kinetics, are polynomial. The  $\text{coefficients of the polynomial equations are }\{\kappa_1,\ldots,\kappa_m\}\subset\mathbb{R}^n_{>0}$  which are called *rate constants*.



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The evolution of the concentration of the species can be modelled with a system of ODEs that, under mass action kinetics, are polynomial. The  $\text{coefficients of the polynomial equations are }\{\kappa_1,\ldots,\kappa_m\}\subset\mathbb{R}^n_{>0}$  which are called *rate constants*.

#### **Key characteristics of the system of ODEs**

- $\triangleright$  One autonomous differential equation per species.
- ▶ As many monomials as linear combinations appearing in the nodes.
- ▶ As many parameters as rate constants.

# **ODEs for Reaction Networks**



For our system

$$
S_0 + E \frac{\kappa_1}{\kappa_2} Y_1 \xrightarrow{\kappa_3} S_1 + E
$$
  
\n
$$
S_1 + F_1 \xrightarrow{\kappa_4} Y_2 \xrightarrow{\kappa_6} S_0 + F_1
$$
  
\n
$$
P_0 + S_1 \xrightarrow{\kappa_7} Y_3 \xrightarrow{\kappa_9} P_1 + S_1
$$
  
\n
$$
P_1 + F_2 \xrightarrow{\kappa_{10}} Y_4 \xrightarrow{\kappa_{12}} P_0 + F_2.
$$

$$
s_0 = -\kappa_1 s_0 e + \kappa_2 y_1 + \kappa_6 y_2
$$
  
\n
$$
s_1 = -\kappa_4 s_1 f_1 - \kappa_7 s_1 \rho_0 + \kappa_3 y_1 + \kappa_5 y_2 + \kappa_8 y_3 + \kappa_9 y_3
$$
  
\n
$$
\rho_0 = -\kappa_7 s_1 \rho_0 + \kappa_8 y_3 + \kappa_1 y_2
$$
  
\n
$$
\rho_1 = -\kappa_1 \rho_1 \rho_2 + \kappa_9 y_3 + \kappa_1 y_1
$$
  
\n
$$
\dot{e} = -\kappa_1 s_0 e + \kappa_2 y_1 + \kappa_3 y_1
$$
  
\n
$$
f_1 = -\kappa_4 s_1 f_1 + \kappa_5 y_2 + \kappa_6 y_2
$$
  
\n
$$
f_2 = -\kappa_1 \rho_1 \rho_2 + \kappa_1 \gamma_1 u_1 + \kappa_1 y_2 u_1
$$
  
\n
$$
y_1 = \kappa_1 s_0 e - \kappa_2 y_1 - \kappa_3 y_1
$$
  
\n
$$
y_2 = \kappa_4 s_1 f_1 - \kappa_5 y_2 - \kappa_6 y_2
$$
  
\n
$$
y_3 = \kappa_7 s_1 \rho_0 - \kappa_8 y_3 - \kappa_9 y_3
$$
  
\n
$$
y_4 = \kappa_1 \rho_1 \rho_2 - \kappa_1 \gamma_4 - \kappa_1 y_2
$$

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# **ODEs for Reaction Networks**



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S_0 + E \frac{\kappa_1}{\kappa_2} Y_1 \xrightarrow{\kappa_3} S_1 + E
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\n
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P_0 + S_1 \xrightarrow{\kappa_7} Y_3 \xrightarrow{\kappa_9} P_1 + S_1
$$
  
\n
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P_1 + F_2 \xrightarrow{\kappa_{10}} Y_4 \xrightarrow{\kappa_{12}} P_0 + F_2.
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$$
s_0 = -\kappa_1 s_0 e + \kappa_2 y_1 + \kappa_6 y_2
$$
  
\n
$$
s_1 = -\kappa_4 s_1 f_1 - \kappa_7 s_1 \rho_0 + \kappa_3 y_1 + \kappa_5 y_2 + \kappa_8 y_3 + \kappa_9 y_3
$$
  
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\rho_0 = -\kappa_7 s_1 \rho_0 + \kappa_8 y_3 + \kappa_1 y_2
$$
  
\n
$$
\rho_1 = -\kappa_1 \rho_1 \rho_2 + \kappa_9 y_3 + \kappa_1 y_1
$$
  
\n
$$
\dot{e} = -\kappa_1 s_0 e + \kappa_2 y_1 + \kappa_3 y_1
$$
  
\n
$$
f_1 = -\kappa_4 s_1 f_1 + \kappa_5 y_2 + \kappa_6 y_2
$$
  
\n
$$
f_2 = -\kappa_1 \rho_1 \rho_2 + \kappa_1 \gamma_1 u_1 + \kappa_1 y_2 u_1
$$
  
\n
$$
y_1 = \kappa_1 s_0 e - \kappa_2 y_1 - \kappa_3 y_1
$$
  
\n
$$
y_2 = \kappa_4 s_1 f_1 - \kappa_5 y_2 - \kappa_6 y_2
$$
  
\n
$$
y_3 = \kappa_7 s_1 \rho_0 - \kappa_8 y_3 - \kappa_9 y_3
$$
  
\n
$$
y_4 = \kappa_1 \rho_1 \rho_2 - \kappa_1 \gamma_4 - \kappa_1 y_2
$$

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### **ODEs for Reaction Networks**



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P_1 + F_2 \xrightarrow{\kappa_{10}} Y_4 \xrightarrow{\kappa_{12}} P_0 + F_2.
$$

$$
s_0 = -\kappa_1 s_0 e + \kappa_2 y_1 + \kappa_6 y_2
$$
  
\n
$$
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$$
  
\n
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$$
  
\n
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\rho_1 = -\kappa_1 \rho_0 + \kappa_2 y_3 + \kappa_1 y_4
$$
  
\n
$$
\dot{e} = -\kappa_1 \rho_5 e + \kappa_2 y_1 + \kappa_3 y_1
$$
  
\n
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f_1 = -\kappa_4 s_1 f_1 + \kappa_5 y_2 + \kappa_6 y_2
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$$
  
\n
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$$
  
\n
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\dot{y}_2 = \kappa_4 s_1 f_1 - \kappa_5 y_2 - \kappa_6 y_2
$$
  
\n
$$
\dot{y}_3 = \kappa_7 s_1 \rho_0 - \kappa_8 y_3 - \kappa_9 y_3
$$
  
\n
$$
\dot{y}_4 = \kappa_{10} \rho_1 f_2 - \kappa_{11} y_4 - \kappa_{12} y_4
$$

 $s<sub>1</sub>$ <sup> $\cdot$ </sup>

$$
\dot{s_0} = -\kappa_1 s_0 e + \kappa_2 y_1 + \kappa_6 y_2
$$

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**KORKAR KERKER DRA** 

Consider a system of ODEs parametrized by  $\mu \in \mathbb{R}$ :

$$
\dot{x}=f_{\mu}(x),
$$

where  $x \in \mathbb{R}^n$ , and  $f_\mu(x)$  varies smoothly in  $\mu$  and  $x$ . Assume that  $f_{\mu_0}(\mathsf{x}_0)=0$ , and assume that there is a smooth curve of steady states:

$$
\mu \ \mapsto \ x(\mu)
$$

(that is,  $f_\mu(x(\mu)) = 0$  for all  $\mu$ ) such that  $x(\mu_0) = x_0$ .



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(that is,  $f_\mu(x(\mu)) = 0$  for all  $\mu$ ) such that  $x(\mu_0) = x_0$ .

A simple Hopf bifurcation occurs at  $\mu_0$  if the matrix  $J_f(x_0, \mu_0)$  has a simple pair of imaginary eigenvalues, while all other eigenvalues remain with negative real part.



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#### **Example**

Consider the system of ODEs

$$
\dot{x} = -y + x(\mu - x^{2} - y^{2})
$$

$$
\dot{y} = x + y(\mu - x^{2} - y^{2})
$$

The only steady state is  $(0, 0)$  which is independent of  $\mu$ .



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#### **Example**

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$$

$$
\dot{y} = x + y(\mu - x^{2} - y^{2})
$$

The only steady state is  $(0, 0)$  which is independent of  $\mu$ . We have

$$
J_f((0,0),\mu) = \left[\begin{array}{cc} \mu & -1 \\ 1 & \mu \end{array}\right]
$$

with eigenvalues  $-i + \mu$  and  $i + \mu$ .



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#### **Example**

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$$
\dot{x} = -y + x(\mu - x^{2} - y^{2})
$$

$$
\dot{y} = x + y(\mu - x^{2} - y^{2})
$$

The dynamics of the system change depending on the value of *µ*.





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#### **Our goal...**

Decide whether there are values for the parameters such that a Hopf bifurcation arises in the subsystem.



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Decide whether there are values for the parameters such that a Hopf bifurcation arises in the subsystem.

#### **Ingredients**







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#### **Our goal...**

Decide whether there are values for the parameters such that a Hopf bifurcation arises in the subsystem.

#### **Ingredients**

- $\blacktriangleright$  Equilibria
- ▶ Are the dynamics constrained to a lower-dimensional space?



**KORK EXTERNEY ORA** 

#### **Our goal...**

Decide whether there are values for the parameters such that a Hopf bifurcation arises in the subsystem.

#### **Ingredients**

- $\blacktriangleright$  Equilibria
- ▶ Are the dynamics constrained to a lower-dimensional space?
- ▶ Eigenvalues of the Jacobian of the polynomials defining the ODEs at equilibrium

# **Equilibria for CRN**



**KORKARA REPASA DA VOCA** 

The positive steady states are defined as equilibrium points of the ODE that have positive entries. That is, the points in  $\mathbb{R}^n_{>0}$  such that  $\dot{\mathsf{x}}=0.$ 

# **Equilibria for CRN**



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The positive steady states are defined as equilibrium points of the ODE that have positive entries. That is, the points in  $\mathbb{R}^n_{>0}$  such that  $\dot{\mathsf{x}}=0.$ 

#### **Example**

For our system, the positive steady states are defined by the equations

$$
0 = -\kappa_1 s_0 e + \kappa_2 y_1 + \kappa_6 y_2
$$
  
\n
$$
0 = -\kappa_4 s_1 f_1 - \kappa_7 s_1 p_0 + \kappa_3 y_1 + \kappa_5 y_2 + \kappa_8 y_3 + \kappa_9 y_3
$$
  
\n
$$
0 = -\kappa_7 s_1 p_0 + \kappa_8 y_3 + \kappa_{12} y_4
$$
  
\n
$$
0 = -\kappa_{10} p_1 f_2 + \kappa_9 y_3 + \kappa_{11} y_4
$$
  
\n
$$
0 = -\kappa_{15} s_0 e + \kappa_2 y_1 + \kappa_3 y_1
$$
  
\n
$$
0 = -\kappa_{16} s_1 f_1 + \kappa_5 y_2 + \kappa_6 y_2
$$
  
\n
$$
0 = -\kappa_{10} p_1 f_2 + \kappa_{11} y_4 + \kappa_{12} y_4
$$
  
\n
$$
0 = \kappa_1 s_0 e - \kappa_2 y_1 - \kappa_3 y_1
$$
  
\n
$$
0 = \kappa_4 s_1 f_1 - \kappa_5 y_2 - \kappa_6 y_2
$$
  
\n
$$
0 = \kappa_7 s_1 p_0 - \kappa_8 y_3 - \kappa_9 y_3
$$
  
\n
$$
0 = \kappa_{10} p_1 f_2 - \kappa_{11} y_4 - \kappa_{12} y_4
$$
  
\n
$$
s_0, s_1, p_0, p_1, e, f_1, f_2, y_i \in \mathbb{R}^n_+
$$



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The steady states can be parameterized as

$$
\varphi(s_0, s_1, p_1, f_1, y_3) = \left(s_0, s_1, \frac{(k_8 + k_9) y_3}{k_7 s_1}, p_1, \frac{(k_2 + k_3) k_4 k_6 s_1 f_1}{k_1 k_3 (k_5 + k_6) s_0}, f_1, \frac{k_9 (k_{11} + k_{12}) y_3}{k_{10} k_{12} p_1}, \frac{k_4 k_6 s_1 f_1}{k_3 (k_5 + k_6)}, \frac{k_4 s_1 f_1}{k_5 + k_6}, y_3, \frac{k_9 y_3}{k_{12}}\right)
$$

### **Conservation laws in CRN**



**KORK EXTERNEY ORA** 

Given an initial solution  $x_0$  for the system of ODEs, the trajectories containing  $x_0$ , remain in  $x_0 + S$  for a linear space *S* (*Stoichiometric compatibility class*). Therefore, we study the dynamics of the network within  $x_0 + S$ .

### **Conservation laws in CRN**



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**Example**

In our system the compatibility classes are defined by the equations

$$
s_0 + s_1 + y_1 + y_2 + y_3 = T_1
$$
  
\n
$$
p_0 + p_1 + y_3 + y_4 = T_2
$$
  
\n
$$
e + y_1 = T_3
$$
  
\n
$$
f_1 + y_2 = T_4
$$
  
\n
$$
f_2 + y_4 = T_5.
$$

These come precisely from the linear relations among the equations defining the system of ODEs.

### **Conservation laws in CRN**



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Indeed, consider the conservation law

$$
f_2+y_4=\,T_5.
$$

The ODEs associated with  $f_2$  and  $y_4$  are

$$
\dot{f}_2 = -\kappa_{10} p_1 f_2 + \kappa_{11} y_4 + \kappa_{12} y_4
$$
  

$$
\dot{y}_4 = \kappa_{10} p_1 f_2 - \kappa_{11} y_4 - \kappa_{12} y_4
$$

whose sum vanishes, that is,  $\dot{f}_2 + \dot{y}_4 = 0,$  which implies the conservation law above.

### **Dynamics of CRN**



#### **Intuitively...**





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**There is hope!** There is no need to compute the exact value of the eigenvalues

Liu's criterion for Hopf bifurcations

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 $\mathbf{E} = \mathbf{A} \oplus \mathbf{B} + \mathbf{A} \oplus \mathbf{B} + \mathbf{A} \oplus \mathbf{B} + \mathbf{A} \oplus \mathbf{A}$ 



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Denote the characteristic polynomial of  $J_{f_\mu}(\mathsf{x}(\mu))$  as

$$
\rho_\mu(\lambda) := \det \big( \lambda I - J_{f_\mu} \big) \, |_{x = x(\mu)} = \lambda^n + b_1(\mu) \lambda^{n-1} + \cdots + b_n(\mu).
$$

Since the coefficients of  $p_\mu(\lambda)$  depend on  $\mu$ , its Hurwitz determinants depend on  $\mu$  as well. We denote each determinant by  $H_i(\mu)$ , for  $i = 1, \ldots, n$ .



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#### **Liu's criterion**

There is a simple Hopf bifurcation at  $x_0$  with respect to  $\mu$  if and only if the following conditions hold:

1.  $b_n(\mu_0) > 0$ , **2.** *H*<sub>1</sub>( $\mu$ <sub>0</sub>) > 0, *H*<sub>2</sub>( $\mu$ <sub>0</sub>) > 0, *...*, *H*<sub>*n*-2</sub>( $\mu$ <sub>0</sub>) > 0, and **3.**  $H_{n-1}(\mu_0) = 0$  and  $\frac{d(H_{n-1}(\mu))}{d\mu}|_{\mu=\mu_0} \neq 0$ .



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#### **Definition (Hurwitz determinants)**

Let  $p(x) = a_s x^s + a_{s-1} x^{s-1} + \ldots + a_1 x + a_0$  be a polynomial with  $a_i \in \mathbb{R}$ ,  $a<sub>s</sub> > 0$  and  $a<sub>0</sub> \neq 0$ . Define the Hurwitz matrix associated with *p*, as the matrix *H* whose entries are defined by  $h_{i,j} = a_{s-2j+i}$  for  $i, j = 1, \ldots, s$  and  $a_k = 0$  if  $k < 0$  or  $k > s$ :

$$
H = \left(\begin{array}{cccccc} a_{s-1} & a_s & 0 & 0 & \cdots & 0 \\ a_{s-3} & a_{s-2} & a_{s-1} & a_s & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & a_{6-s} & \cdots & a_2 \\ 0 & 0 & 0 & 0 & \cdots & a_0 \end{array}\right)
$$

The *i*-th Hurwitz determinant of *H*, denoted by *H<sup>i</sup>* , is defined as  $H_i = \det(H_i)$ , with  $I = \{1, \ldots, i\}$ .



**KORKARA REPASA DA VOCA** 

#### **Results**

▶ The characteristic polynomial of the Jacobian restricted to a stoichiometric compatibility class has degree 6.



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- $\blacktriangleright$  The characteristic polynomial of the Jacobian restricted to a stoichiometric compatibility class has degree 6.
- $\triangleright$  We computed 6 Hurwitz determinants:  $\{H_1, \ldots, H_6\}$  and evaluated them at the parameterization of the steady states.



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- $\blacktriangleright$  *H*<sub>1</sub>, *H*<sub>2</sub>, *H*<sub>3</sub>, and *H*<sub>6</sub> are rational functions (in 6 variables and 17 parameters) with positive coefficients.



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A Hopf bifurcation appears if there is a set of parameters *κ ∗* and an steady state *x ∗* such that

$$
H_4(k^*, x^*) \ge 0
$$
 and  $H_5(k^*, x^*) = 0$ .



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#### **Proposition**

For a real, multivariate polynomial

$$
p(x) = a_1x^{\alpha_1} + a_2x^{\alpha_2} + \cdots + a_{\ell}x^{\alpha_{\ell}} \in \mathbb{R}[x_1,\ldots,x_n],
$$

if  $\alpha_i$  is a vertex of  $\mathsf{Newt}(p)$ , then there exists  $\mathsf{x}^* \in \mathbb{R}_{>0}^n$  such that  $sign(p(x^*)) = sign(a_i).$ 



**KORKAR KERKER DRAM** 

#### **Proposition**

For a real, multivariate polynomial

$$
p(x) = a_1 x^{\alpha_1} + a_2 x^{\alpha_2} + \cdots + a_\ell x^{\alpha_\ell} \in \mathbb{R}[x_1, \ldots, x_n],
$$

if  $\alpha_i$  is a vertex of  $\mathsf{Newt}(p)$ , then there exists  $\mathsf{x}^* \in \mathbb{R}_{>0}^n$  such that  $sign(p(x^*)) = sign(a_i).$ 

#### **Proposition**

Let  $f, g \in \mathbb{R}[x_1, x_2, \ldots x_s]$ . Assume that  $\alpha$  is a positive vertex of  $\text{Newt}(f)$ , *β*<sup>+</sup> is a positive vertex of Newt(*g*), and *β<sup>−</sup>* is a negative vertex of  $Newt(g)$ . Then, if  $int(N_f(\alpha)) \cap int(N_g(\beta_+))$  and  $\mathrm{int}(N_f(\alpha))\cap\mathrm{int}(N_g(\beta_-))$  are both nonempty, then there exists  $x^*\in\mathbb{R}_{>0}^s$ such that  $f(x^*) > 0$  and  $g(x^*) = 0$ .





![](_page_42_Figure_1.jpeg)

**KORKARA REPASA DA VOCA** 

Applying the previous propositions in a reduced version of  $H_4$  and  $H_5$  we found the following parameters that satisfy Liu's criterion.

*s*<sup>0</sup> =0*.*008221823730*,s*<sup>1</sup> = 8*.*670580350 *×* 10*−*<sup>7</sup> *, p*<sup>0</sup> = 1*, p*<sup>1</sup> = 197868*.*6638*, e* =0*.*007561436673*, f*<sup>1</sup> = 1*, f*<sup>2</sup> = 0*.*007884719363*, y*<sup>1</sup> = 0*.*001238422300*, y*<sup>2</sup> =0*.*001238422300*, y*<sup>3</sup> = 0*.*5461508658*, y*<sup>4</sup> = 780*.*0694426

with parameters

 $\kappa_1$  = 20*,*  $\kappa_2$  = 0.004*,*  $\kappa_3$  = 1*,*  $\kappa_4$  = 1428*.*303957*,*  $\kappa_5$  = 9.941572972  $\times$  10<sup>-8</sup>  $\kappa_6 =$   $1, \kappa_7 =$   $9.941572972 \times 10^8, \kappa_8 =$   $150, \kappa_9 =$   $1428.303957,$  $\kappa_{10} = 1, \kappa_{11} = 1, \kappa_{12} = 1,$ *T*<sup>1</sup> =0*.*5568504012*,T*<sup>2</sup> = 198650*.*2794*, T*<sup>3</sup> =0*.*008799858973*,T*<sup>4</sup> = 1*.*001238422*,T*<sup>5</sup> = 780*.*0773273

![](_page_43_Picture_1.jpeg)

![](_page_43_Figure_2.jpeg)

 $4$  ロ }  $4$   $6$  }  $4$   $3$  }  $4$  $\equiv$ Ğ,  $299$  $\mathbf{p}$ 

![](_page_44_Picture_1.jpeg)

![](_page_44_Figure_2.jpeg)

イロメ イ部メ イ君メ イ君メー  $\equiv$  990

### **Remaining questions**

![](_page_45_Picture_1.jpeg)

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- $\blacktriangleright$  Are these parameters meaningful biologically?
- ▶ Is there a good implementation to speed up computations of Hurwitz determinants?

### **Remaining questions**

![](_page_46_Picture_1.jpeg)

**KORKARA REPASA DA VOCA** 

- $\blacktriangleright$  Are these parameters meaningful biologically?
- ▶ Is there a good implementation to speed up computations of Hurwitz determinants?

#### **References**

- - C. Y. Huang and J. E. Ferrell.

Ultrasensitivity in the mitogen-activated protein kinase cascade. *Proc. Natl. Acad. Sci. U.S.A.*, 93:10078–10083, 1996

**I** L. Qiao, R. B. Nachbar, I. G. Kevrekidis, and S. Y. Shvartsman. Bistability and oscillations in the Huang-Ferrell model of MAPK signaling. *PLoS Comput. Biol.*, 3(9):1819–1826, 2007.

### **Remaining questions**

![](_page_47_Picture_1.jpeg)

**KORKARA REPASA DA VOCA** 

- $\blacktriangleright$  Are these parameters meaningful biologically?
- ▶ Is there a good implementation to speed up computations of Hurwitz determinants?

#### **References**

- - **C.** Y. Huang and J. E. Ferrell.

Ultrasensitivity in the mitogen-activated protein kinase cascade. *Proc. Natl. Acad. Sci. U.S.A.*, 93:10078–10083, 1996

**i** L. Qiao, R. B. Nachbar, I. G. Kevrekidis, and S. Y. Shvartsman. Bistability and oscillations in the Huang-Ferrell model of MAPK signaling.

*PLoS Comput. Biol.*, 3(9):1819–1826, 2007.

# Danke<sup>l</sup>